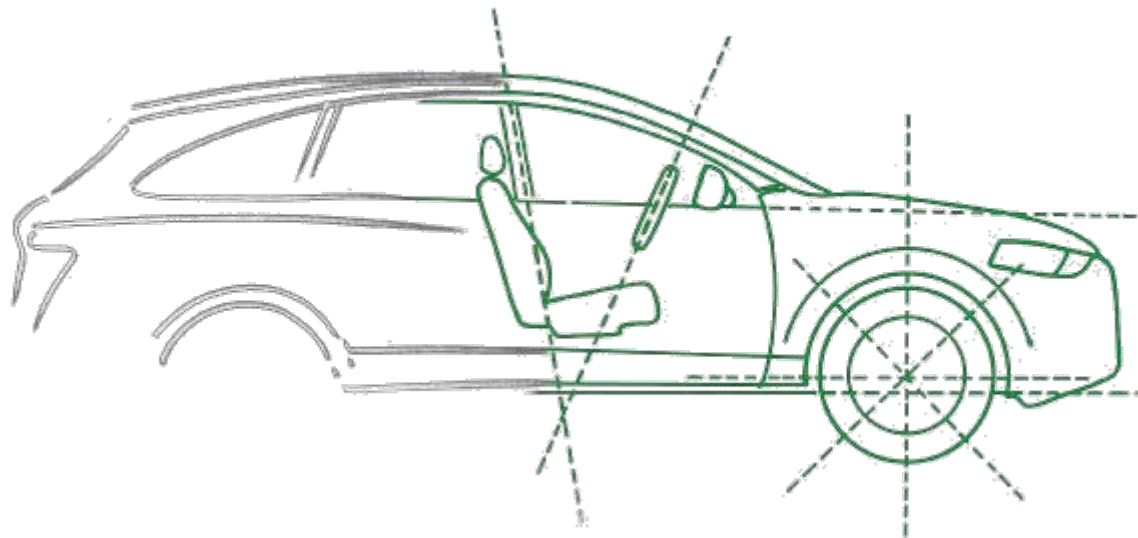




# Modeling requirements to support testing of product-lines



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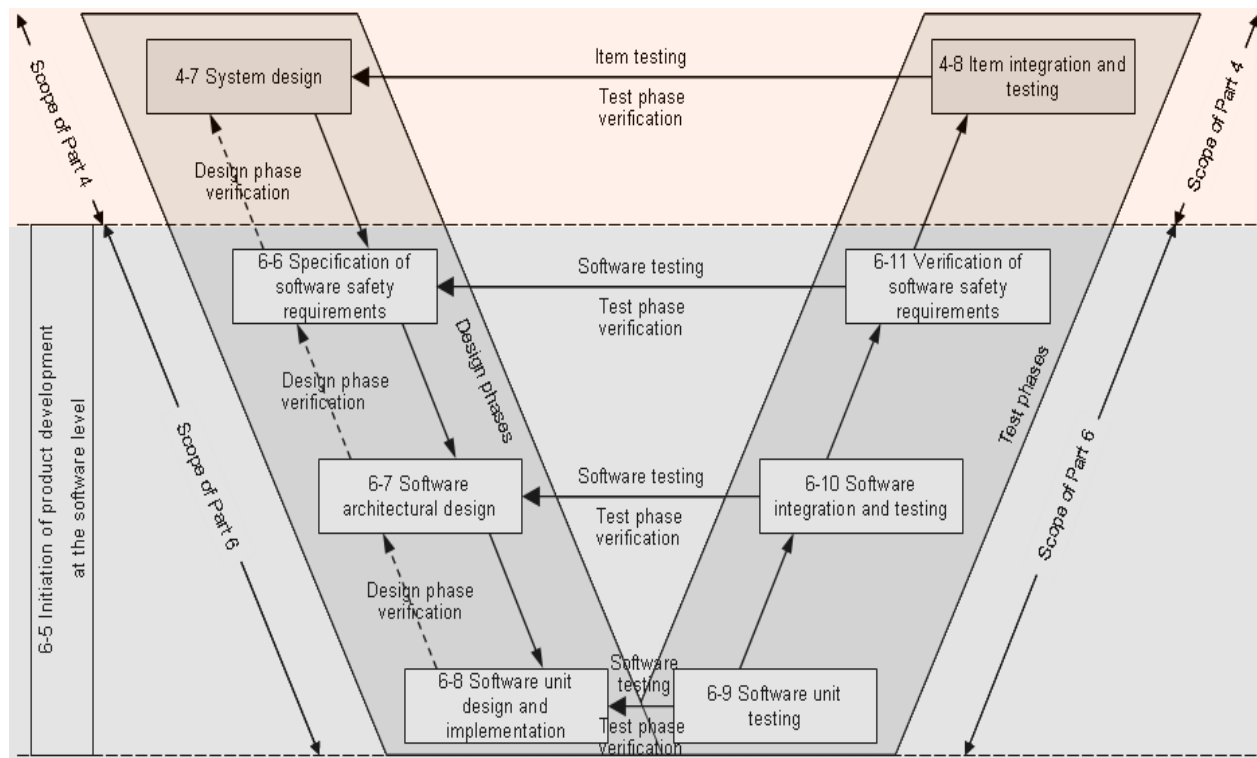
# Overview

- RE/RM and test-management in practice (with DOORS)
- Model-based specification and analysis
- Variant-management for specifications
- Berner & Mattner MERAN for IBM Rational DOORS
- Applications and experiences



# Automotive Industry Context of MBA and MBT of Systems

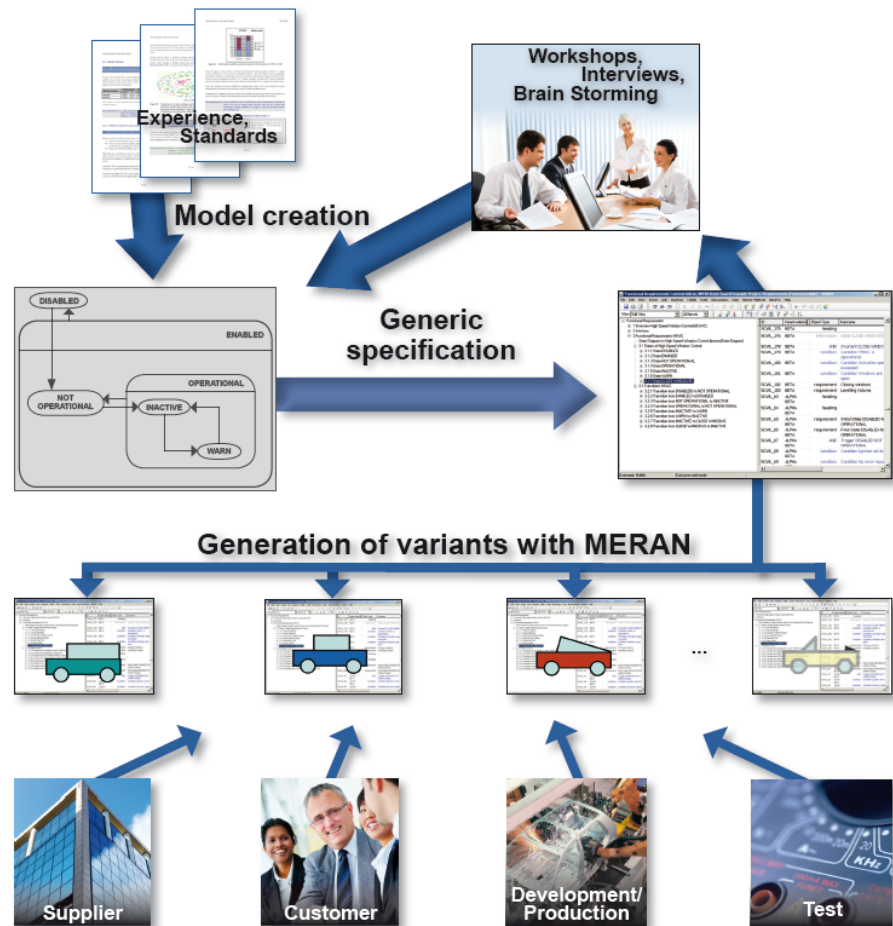
- ISO 26262 will soon be obligatory
- ISO 26262 part 4 regulates system analysis and validation
- Requirements are input for Item integration and testing analysis
- MBT and MBA shall be applied during *Item Integration and Testing*





# Model-based requirements writing process

- Interviews and Workshop
- Model definition (e.g. Statecharts)
- Specification structure follows model
- Elicitation and integration of requirements
- Iterative analysis, refinement and completion of requirements



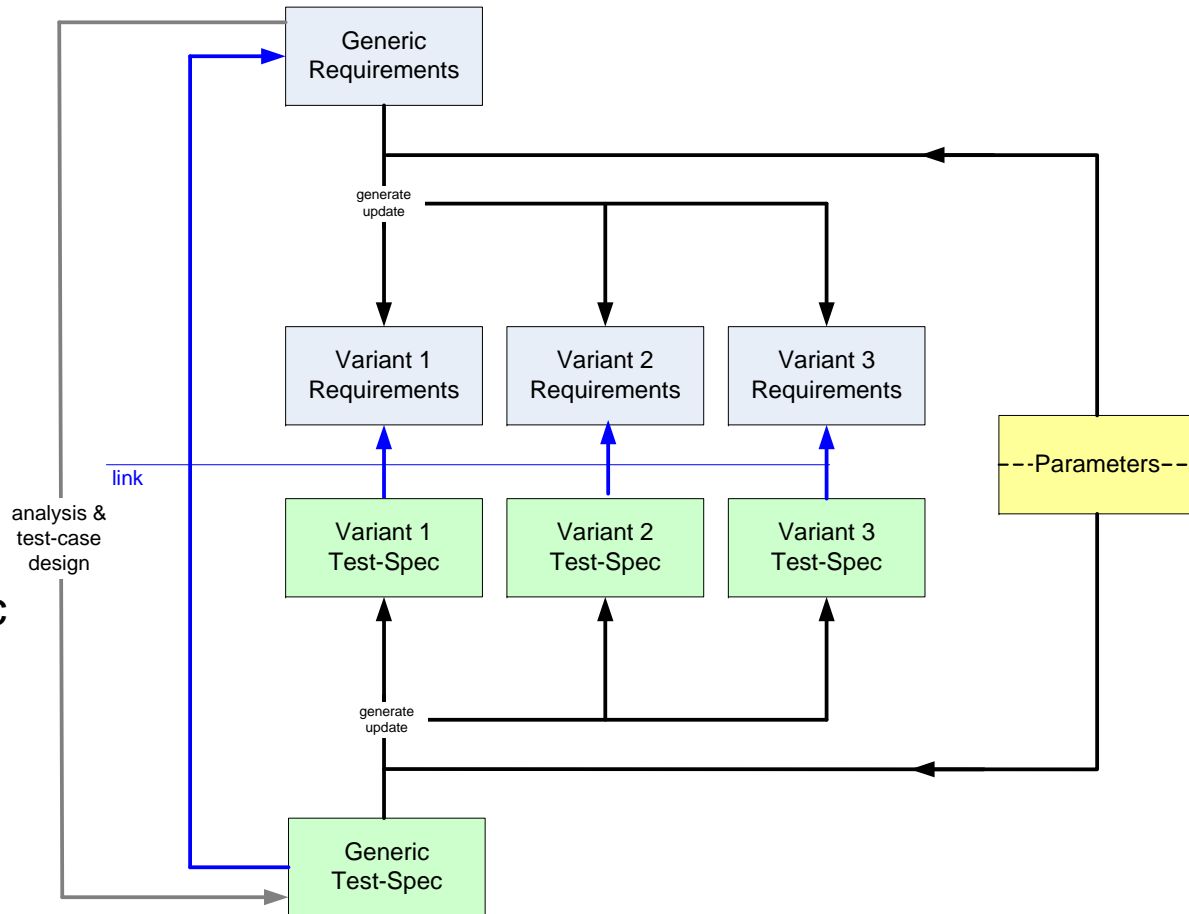
## optional steps

- Specification of *complete* test-cases
- Implementation of executable test-cases
- Formal analyses and approvals



# Specification and testing of product-lines

- generic requirements specification is created for product-line
- Options
  - create generic test-case specs and generate specific test-cases
  - create specific test-cases for specific requirements
- a mutual parameter base may reduce risk of inconsistencies between requirements and test-cases





# Model-based Specification

- Structure of a specification follows a functional model
- Semi-formal specification of states and transitions
- Semi-formal specification of conditions

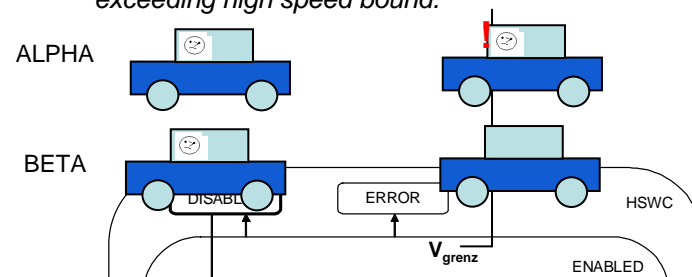
## Advantages

- Intuitively comprehensible, functional structure
- Improved
  - changeability
  - analysability
  - testability
- accepted redundancies only
- great basis for following model-based development, testing and analyses

### Example HSWC:

Function High Speed Window Control in variant ALPHA warn on opened window exceeding high speed bound.

Function HSWC in variant BETA, closes windows autonomously on exceeding high speed bound.



### Chapter X Functional requirements HSWC

#### Chapter X.1 States

- Chapter X.1.1 State HSWC
- Chapter X.1.2 State DISABLED
- Chapter X.1.3 State ENABLED
- Chapter X.1.4 State NOT OPERATIONAL
- Chapter X.1.5 State OPERATIONAL
- Chapter X.1.6 State INACTIVE
- Chapter X.1.7 State ACTIVE
- Chapter X.1.8 State ERROR

#### Chapter X.2 Transitions

- Chapter X.2.1 Transition DISABLED-NOT OPERATIONAL
- Chapter X.2.2 Transition ENABLED-DISABLED
- Chapter X.2.3 Transition NOT OPERATIONAL-INACTIVE
- Chapter X.2.4 Transition OPERATIONAL-NOT OPERATIONAL
- Chapter X.2.5 Transition INACTIVE-ACTIVE
- Chapter X.2.6 Transition ACTIVE-INACTIVE
- Chapter X.2.7 Transition ENABLED-ERROR



# Typed Specifications

- Specifications contain
  - identifiable
  - atomic
  - typed objects
- Requirements, must be distinguishable from structure, explanations and comments
- Typing allows application of automated analysis and processing

## *basic specification types*

Type	description
heading	structure elements
information	explanations or comments
requirement	separated required product property

## *conditional specification types*

Type	description
XOR	exclusive disjunctive composition of conditions
OR	disjunctive composition of conditions
AND	conjunctive composition of conditions
condition	atomic conditional requirement





# State Specification

- State specification template
  - explanatory information including short name
  - optional sub-states and initial state
  - optional state invariant
  - additional state-related requirements

*Example HSWC State Operational*

Type	ALPHA	BETA	Name	Text
heading	X	X		X.1.5 State OPERATIONAL
information	X	X	State OPERATIONAL	The state OPERATIONAL represents the operational function HSWC.
requirement	X	X	Sub-states OPERATIONAL	State OPERATIONAL includes State INACTIVE and State ACTIVE.
requirement	X	X	Initial State OPERATIONAL	The initial sub-state in State OPERATIONAL is State INACTIVE.
AND	X	X	Condition Operation HSWC	The function HSWC is operational, if every of the following conditions hold:
condition	X	X	Condition HSWC is enabled	•The function HSWC is enabled; in State ENABLED.
condition	X	X	Condition Operation Speed exceeded	•The vehicle speed is greater or equals $V_{Operation}$ .
condition		X	Condition No rear-seat passengers	•On the rear-seats no passengers are detected.
requirement	X	X	Additional Requirement	HSWC shall ...





# Transition Specification

- Transition Specification Template
  - explanatory information including short name
  - initial state
  - final state
  - trigger condition
  - transition-related requirements

## *Example HSWC Transition Inactive to Active*

Type	ALPHA	BETA	Name	Text
heading	X	X		X.1.4 Transition from INACTIVE to ACTIVE
information	X	X	Transition INACTIVE-ACTIVE	The transition from state INACTIVE to state ACTIVE represents the activation of HSWC.
requirement	X	X	Initial State	The initial state is State INACTIVE.
requirement	X	X	Final State	The final state is State ACTIVE.
AND	X	X	Condition Activation HSWC	The function HSWC is activated if every of the following conditions hold:
condition	X	X	Condition HSWC is operational	•The function HSWC is operation; the function is in State OPERATIONAL.
condition	X	X	Condition Windows are open	•At least one window is open.
condition	X	X	Condition Vehicle exceeding $v_{act}$	•The vehicle speed is greater or equals $v_{Activation}$ .
requirement		X	Command closing windows.	On activation of HSWC windows must be commanded to close.
requirement	X		Activation Message	On activation of HSWC a message must be displayed to the driver.
requirement	X	X	Activity Report	On activation of HSWC the activity bit has to be set.



# Test-case specification

- Test-case specification template

- Optional pre-conditions
- Test-steps

## Attributes

- Precondition
- Action
- Measurement
- Postcondition
- ...

- Optional post-conditions

- Further Extensions

- Code-Steps
- Test-runs

type	description
test-case	containing pre-/post-conditions, and test-steps
pre-condition	initial system state
test-step	separated input and response pairs
post-condition	final system state



# Generic Test-case Specification

- Test-case specification may reuse variant definitions
- Test-case specifications may extend variant definitions
- Test-case design
  - Functional Coverage
  - Combinatorial Testing
  - Sequence Enumeration
  - Search-based Testing

*Example Test-case for HSWC Transition Inactive to Active*

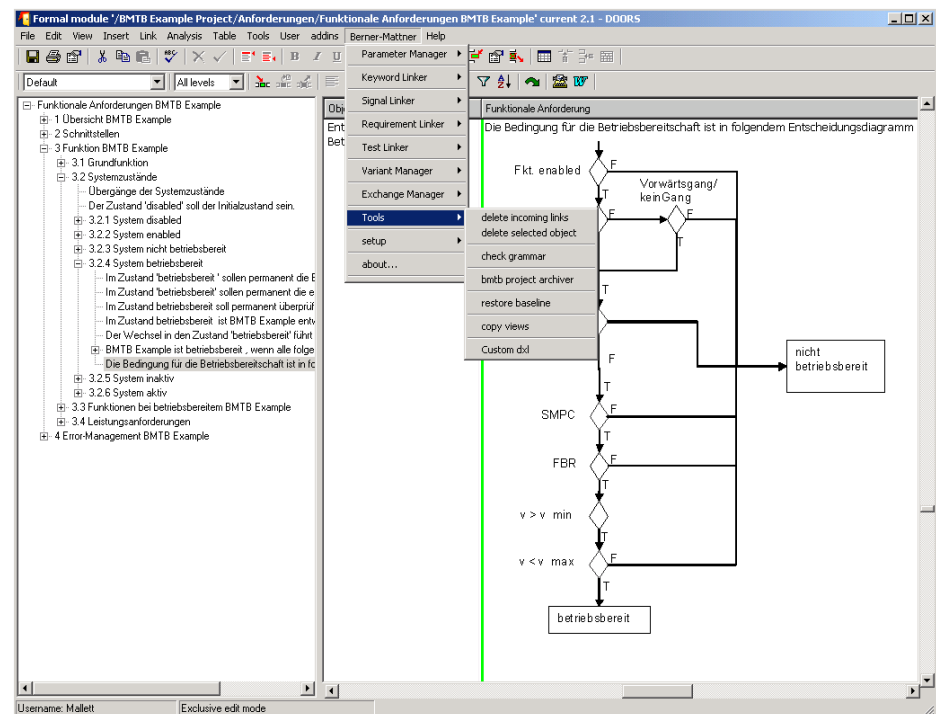
Type	Mark		Purpose		Input	Expected Response
	ALPHA	BETA	positive	negative		
test-case	X	X	X	X		
pre-condition	X	X	X	X	HSWC is in state INACTIVE	
pre-condition	X	X	X	X	HSWC is operational	
test-step	X	X	X		Open rear-windows.	Windows are opening.
test-step	X	X		X	Close any windows.	Windows are closed.
test-step	X	X	X		Accelerate car to a speed of $v_{activation}$	Car speed is equal or greater $v_{activation}$
test-step	X	X		X	Accelerate car to a speed of $(v_{activation} - 1)$	Car speed is less than $v_{activation}$
post-condition		X	X	X		Signal 'Close Windows' emitted.
post-condition	X		X	X		Signal 'Close Windows' not emitted.
post-condition	X		X	X		Warning message is displayed.



# MERAN for IBM Rational DOORS

## Features

- Variant-Management
- Automatised management of keywords and signals lists
- Automatised indexing
- Automatised linking
- Test-management over a whole product-line
- Test-automation in DOORS
- Improved DOORS handling
- Automatic generation of statistics
- Extended data exchange, e.g. Excel, mind-maps, Visio
- Combinatorial testing tool
- Model-based analysis and testing tool





# Experiences and Applications

## *Experiences*

- theoretical expense reduction  $(n-1)$ , where  $n$  is the number of variants, is barely producible in practice, but we
  - frequently reduce specification size by 30 % due to model-based approach
  - frequently reduce expenses by up to 50 % due to variant-management
- these figures are useful planning guidelines, based on experiences from more than 20 projects
- empirical validation has to be done

## *Applications*

- Variant-Management of **Parking Systems** at **Daimler AG**
- Model-based specification and variant-management of several brake-assistance systems at **Daimler AG**
- Development and deployment of a car-platform- and company wide test-management system for the functional integration at **Volkswagen AG**
- Variant-management for the specification of a flight-system at **Airbus**



# Summary

- Specifications often of low quality
- High expenses for adopting MBA/MBT
- Model-based approach may result in better requirements and enables efficient variant-management
- Effort savings in requirements and test specifications



End.





# Appendix 1: Generic module HSWC

'Functional Requirements' current 0.0 in /BMTB State-based Example Project/Requirements (Formal module) - DOORS

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View Edit View All levels

State Diagram for High Speed Window Control #p4

- 3.1 States of High Speed Window Control
  - 3.1.1 State DISABLED
  - 3.1.2 State ENABLED
    - The State ENABLED represents the active state of the function HSWC.
    - The State ENABLED contains the State OPERATIONAL.
    - The initial state of State Enabled is State NOT OPERATIONAL.
    - The function HSWC is in State ENABLED.
  - 3.1.3 State NOT OPERATIONAL
    - The State NOT OPERATIONAL represents the state where the function HSWC is not active.
    - The function HSWC is in State NOT OPERATIONAL.
    - The function HSWC is suppressed, if a warning message is displayed on the DDU, while the function HSWC is in State OPERATIONAL.
    - The speed of the system vehicle is below #param[Lower Activation Speed Bound].
    - The function HSWC is suppressed, if the rear-window is locked to the rear-seats passengers.
    - On the rear-seats passengers.
    - When State NOT OPERATIONAL is entered, the function HSWC is suppressed.
    - In State NOT OPERATIONAL the function HSWC is suppressed.
  - 3.1.4 State OPERATIONAL
  - 3.1.5 State INACTIVE
  - 3.1.6 State WARN
  - 3.1.7 State CLOSE WINDOWS
- 3.2 Transitions HSWC
  - 3.2.1 Transition from DISABLED to NOT OPERATIONAL
  - 3.2.2 Transition from ENABLED to DISABLED
  - 3.2.3 Transition from NOT OPERATIONAL to INACTIVE
  - 3.2.4 Transition from OPERATIONAL to NOT OPERATIONAL
  - 3.2.5 Transition from INACTIVE to WARN
  - 3.2.6 Transition from WARN to INACTIVE
  - 3.2.7 Transition from INACTIVE to CLOSE WINDOWS
  - 3.2.8 Transition from CLOSE WINDOWS to INACTIVE

Variants	Object Type	Kurzname	Funktionale Anforderung	Referenzen
ALPHA BETA	condition	Condition Activation speed not exceeded	<ul style="list-style-type: none"> <li>• The system vehicle speed is below #param[Lower Activation Speed Bound].</li> </ul>	SCWL_KEY_1: system vehicle
ALPHA	heading		<b>3.1.6 State WARN</b>	
ALPHA	information	State WARN	The state WARN represents the warning enabled by the function HSWC, when exceeding the upper activation speed bound.	
ALPHA	AND	Invariant INACTIVE	The function HSWC is in State WARN, if every of the following conditions hold:	SCWL_61: State WARN
ALPHA	condition	Condition HSWC is operational	<ul style="list-style-type: none"> <li>• The function HSWC is in State OPERATIONAL.</li> </ul>	SCWL_54: State OPERATIONAL
ALPHA	condition	Condition Activation speed exceeded	<ul style="list-style-type: none"> <li>• The system vehicle speed exceeds #param[Upper Activation Speed Bound].</li> </ul>	SCWL_KEY_1: system vehicle
ALPHA	requirement	Enable Warning Message	An optical warning message is displayed on the DDU, while the function HSWC is in State WARN.	SCWL_61: State WARN SCWL_126: DDU
BETA	heading		<b>3.1.7 State CLOSE WINDOWS</b>	
BETA	information	State CLOSE WINDOWS	The state CLOSE WINDOWS represents the closing of any open windows enabled by the function HSWC, when exceeding the upper activation speed bound.	
BETA	AND	Invariant CLOSE WINDOWS	The function HSWC is in State CLOSE WINDOWS, if every of the following conditions hold:	SCWL_176: State CLOSE WINDOWS
BETA	condition	Condition HSWC is operational	<ul style="list-style-type: none"> <li>• The function HSWC is in State OPERATIONAL.</li> </ul>	SCWL_54: State OPERATIONAL
BETA	condition	Condition Activation speed exceeded	<ul style="list-style-type: none"> <li>• The system vehicle speed exceeds #param[Upper Activation Speed Bound].</li> </ul>	SCWL_KEY_1: system vehicle
BETA	condition	Condition Windows are open	<ul style="list-style-type: none"> <li>• The WCU signals at least one open window.</li> </ul>	SCWL_124: WCU SCWL_SIG_1:
BETA	requirement	Closing windows	Any open windows are closed automatically, while the function HSWC is in State CLOSE WINDOWS.	SCWL_176: State CLOSE WINDOWS
BETA	requirement	Levelling Volume	The volume of the stereo system is levelled. #param[Stereo Low	

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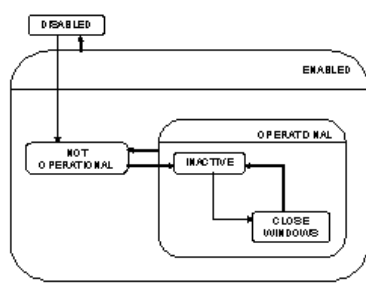
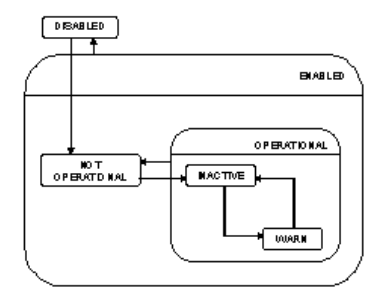


# Appendix 2: Parameter module HSWC

'Parameter' current 0.0 in /BMTB State-based Example Project/Parameter (Formal module) - DOORS

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View Default All levels

Function	Parameter Name	Default Value	BETA Value	ALPHA Value	Parameter Type	Parameter Description
HSWC parameters						
	State Diagram					
	Upper Operational Speed Bound	100		110	[km/h]	The speed limit which
	Lower Operational Speed Bound	90		100	[km/h]	The speed limit which
	Upper Activation Speed Bound	130	120		[km/h]	The volume to set aft of the rage from 0-10
	Lower Activation Speed Bound	120	110		[km/h]	The volume to set aft of the rage from 0-10
	Stereo Low Level	60	50		[dB]	

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# Appendix 3: Variant module ALPHA

'Functional Requirements variant ALPHA' current 0.0 in /BMTB State-based Example Project/Requirements/ALPHA (Formal module) - DOORS

File Edit View Insert Link Analysis Table Tools Discussions User Add-Ons MERAN NeuPro Tau Help

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Functional Requirements variant ALPHA

- 1 Overview High Speed Window Control (HSWC)
  - The goal of the function HSWC is to close the windows of
  - 1.1 Model range and variants
- 2 Interface
- 3 Functional Requirements HSWC
  - State Diagram for High Speed Window Control
  - 3.1 States of High Speed Window Control
    - 3.1.1 State DISABLED
    - 3.1.2 State ENABLED
    - 3.1.3 State NOT OPERATIONAL
    - 3.1.4 State OPERATIONAL
    - 3.1.5 State INACTIVE
    - 3.1.6 State WARN
  - 3.2 Transitions HSWC
    - 3.2.1 Transition from DISABLED to NOT OPERATION
    - 3.2.2 Transition from ENABLED to DISABLED
    - 3.2.3 Transition from NOT OPERATIONAL to INACTIV
    - 3.2.4 Transition from OPERATIONAL to NOT OPERA
    - 3.2.5 Transition from INACTIVE to WARN
    - 3.2.6 Transition from WARN to INACTIVE

ID	Object Type	Kurzname	Funktionale Anforderung	Referenzen
ALPHA_SC WL_59	AND	Invariant INACTIVE	The function HSWC is in <b>State INACTIVE</b> , if every of the following conditions hold:	SCWL_55: State INACTIVE
ALPHA_SC WL_147	condition	Condition HSWC is operational	<ul style="list-style-type: none"> <li>The function HSWC is in <b>State OPERATIONAL</b>.</li> </ul>	SCWL_54: State OPERATIONAL
ALPHA_SC WL_153	condition	Condition Activation speed not exceeded	<ul style="list-style-type: none"> <li>The <u>system vehicle</u> speed is below 120 [km/h].</li> </ul>	SCWL_KEY_1: system vehicle
ALPHA_SC WL_60	heading		<b>3.1.6 State WARN</b>	
ALPHA_SC WL_61	information	State WARN	The state WARN represents the warning enabled by the function HSWC, when exceeding the upper activation speed bound.	
ALPHA_SC WL_149	AND	Invariant INACTIVE	The function HSWC is in <b>State WARN</b> , if every of the following conditions hold:	SCWL_61: State WARN
ALPHA_SC WL_150	condition	Condition HSWC is operational	<ul style="list-style-type: none"> <li>The function HSWC is in <b>State OPERATIONAL</b>.</li> </ul>	SCWL_54: State OPERATIONAL
ALPHA_SC WL_151	condition	Condition Activation speed exceeded	<ul style="list-style-type: none"> <li>The <u>system vehicle</u> speed exceeds 130 [km/h].</li> </ul>	SCWL_KEY_1: system vehicle
ALPHA_SC WL_155	requirement	Enable Warning Message	An optical warning message is displayed on the <u>DDU</u> , while the function HSWC is in <b>State WARN</b> .	SCWL_61: State WARN SCWL_126: DDU
ALPHA_SC WL_63	heading		<b>3.2 Transitions HSWC</b>	
ALPHA_SC WL_64	heading		<b>3.2.1 Transition from DISABLED to NOT OPERATIONAL</b>	
ALPHA_SC WL_65	requirement	Initial State DISABLED-NOT OPERATIONAL	This transition starts in <b>State DISABLED</b> .	SCWL_43: State DISABLED
ALPHA_SC	requirement	Final State DISABLED-NOT	This transition ends in <b>State INACTIVE</b> .	SCWL_58: State INACTIVE

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# Appendix 4: Variant module BETA

'Functional Requirements variant BETA' current 0.0 in /BMTB State-based Example Project/Requirements/BETA (Formal module) - DOORS

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Functional Requirements variant BETA

- [-] 1 Overview High Speed Window Control (HSWC)
  - [-] The goal of the function HSWC is to close the windows
  - [-] 1.1 Model range and variants
- [-] 2 Interface
  - [-] 2.1 System Level
  - [-] 2.2 Component Level
- [-] 3 Functional Requirements HSWC
  - [-] State Diagram for High Speed Window Control
  - [-] 3.1 States of High Speed Window Control
    - [-] 3.1.1 State DISABLED
    - [-] 3.1.2 State ENABLED
    - [-] 3.1.3 State NOT OPERATIONAL
    - [-] 3.1.4 State OPERATIONAL
    - [-] 3.1.5 State INACTIVE
    - [-] 3.1.6 State CLOSE WINDOWS
  - [-] 3.2 Transitions HSWC
    - [-] 3.2.1 Transition from DISABLED to NOT OPERATIONAL
    - [-] 3.2.2 Transition from ENABLED to DISABLED
    - [-] 3.2.3 Transition from NOT OPERATIONAL to INACTIVE
    - [-] 3.2.4 Transition from OPERATIONAL to NOT OPERATIONAL
    - [-] 3.2.5 Transition from WARN to INACTIVE
    - [-] 3.2.6 Transition from INACTIVE to CLOSE WINDOWS
    - [-] 3.2.7 Transition from CLOSE WINDOWS to INACTIVE

ID	Object Type	Kurzname	Funktionale Anforderung	Referenzen
BETA_SC WL_153	condition	Condition Activation speed not exceeded	<ul style="list-style-type: none"> <li>• The <u>system vehicle</u> speed is below 110 [km/h].</li> </ul>	SCWL_KEY_1: system vehicle
BETA_SC WL_175	heading		<b>3.1.6 State CLOSE WINDOWS</b>	
BETA_SC WL_176	information	State CLOSE WINDOWS	The state CLOSE WINDOWS represents the closing of any open windows enabled by the function HSWC, when exceeding the upper activation speed bound.	
BETA_SC WL_178	AND	Invariant CLOSE WINDOWS	The function HSWC is in <b>State CLOSE WINDOWS</b> , if every of the following conditions hold:	SCWL_176: State CLOSE WINDOWS
BETA_SC WL_179	condition	Condition HSWC is operational	<ul style="list-style-type: none"> <li>• The function HSWC is in <b>State OPERATIONAL</b>.</li> </ul>	SCWL_54: State OPERATIONAL
BETA_SC WL_180	condition	Condition Activation speed exceeded	<ul style="list-style-type: none"> <li>• The <u>system vehicle</u> speed exceeds 120 [km/h].</li> </ul>	SCWL_KEY_1: system vehicle
BETA_SC WL_181	condition	Condition Windows are open	<ul style="list-style-type: none"> <li>• The <u>WCU</u> signals at least one open window.</li> </ul>	SCWL_124: WCU SCWL_SIG_1:
BETA_SC WL_182	requirement	Closing windows	Any open windows are closed automatically, while the function HSWC is in <b>State CLOSE WINDOWS</b> .	SCWL_176: State CLOSE WINDOWS
BETA_SC WL_183	requirement	Levelling Volume	The volume of the stereo system is levelled 50 [dB].	
BETA_SC WL_63	heading		<b>3.2 Transitions HSWC</b>	
BETA_SC WL_64	heading		<b>3.2.1 Transition from DISABLED to NOT OPERATIONAL</b>	
BETA_SC WL_65	requirement	Initial State DISABLED-NOT OPERATIONAL	This transition starts in <b>State DISABLED</b> .	SCWL_43: State DISABLED
BETA_SC WL_66	requirement	Final State DISABLED-NOT OPERATIONAL	This transition ends in <b>State INACTIVE</b> .	SCWL_58: State INACTIVE

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